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AN ECCENTRIC SHEAR-LAG MODEL AND IMPLICATIONS ON THE STRENGTH OF FIBROUS COMPOSITES



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Abstract

The stress field in the vicinity of a broken fiber-reinforced composite is analyzed by means of a shear-lag model. The broken filament is positioned eccentrically relative to its neighboring fibers to simulate the commonplace non-uniformity of fiber spacing within the transverse plane. It is shown that a fiber break gives rise to severe bending, in addition to tension, in the neighboring fibers - with a substantial overstress focused on the nearest unbroken filament. The complex nature of the stress field, which is caused by the failure of a fiber within a composite casts doubt on the applicability of failure statistics derived from tensile failure data of single fibers, which is commonly used to predict the strength of composites.

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1. INTRODUCTION

Concentric shear-lag models have been used extensively in the analysis of composites, in particular, in the context of micromechanical aspects of failure (see, for example, Hull, 1981). Indeed, the interplay between micromechanics and the statistics of fiber failure appears to be the most difficult aspect in modeling the strength of fibrous composites.

Due to the complexity of the phenomenon, the theoretical analysis invokes a variety of assumptions, the influence of which may be difficult to assess. One of the basic approaches was set forth by Gucer and Gurland (1962) who represented a material as a series of layers. Each layer was considered to consist of fiber-like elements loaded in parallel, which allows for the use of the bundle theory (Daniels, 1945) to analyze its strength. The overall failure of the layered structure may then be predicted by the weakest link approach. This theory has left, however, the layer thickness unspecified. Rosen (1965), proposed to identify this parameter as the so-called fiber ineffective length, δ , and provided a definition of this quantity.

Since then this approach which combined micromechanical and statistical considerations, has been of particular interest in failure investigations. Garg et, al (1973), provided a good exposition of the approach, which remained of particular interest up to the present time, such as in the recent investigations of composite failure by Prewo (1986) and Schweifert and Steif (1990).

As noted earlier, the models of statistical strength are essentially approximate and invoke various assumptions. A fortuitous agreement with experiments may therefore well occur. It is instructive that a prediction of failure which is based upon the simple-minded rule of mixtures appears to fit the experiments reported by Prewo (1986) fairly well, while a much more sophisticated approach by Zweben and Rosen (1970) provides good results only if the ineffective length is taken to be orders of magnitude larger than the value derived from the theoretical analysis. Thus, it becomes clear that there may be important micromechanical and other factors, which were overlooked by the analysis.

To discuss these factors we recall the basic result given by Rosen (1965) as follows

$$\frac{\sigma_{L}^{*}}{\sigma_{L}} = \left(\frac{\delta}{L}\right)^{-1/\beta} \left(\beta e^{-1/\beta}\right) / \Gamma\left(1 + 1/\beta\right)$$
(1)

Here σ_l^* and σ_L are the statistical mode of composite failure stress and the mean tensile strength of an individual fiber, respectively, δ and L are the ineffective length and the fiber length, respectively, β is an empirical Weibull parameter, and $\Gamma(\cdot)$ is the Gamma function. One observes from Equation (1) that the composite mechanical behavior manifests itself through the ineffective length, δ , while the statistical nature of the phenomenon is introduced through the Weibull parameter, β , which is obtained from failure data for "dry" fibers in pure tension.

There appear to be two major arguments which cast doubt on the accuracy of Equation (1) and its underlying methodology. The first argument, forwarded by McCarthy and Orringer (1975), indicates that statistical strength data obtained for tensile loading of fibers involve samples with lengths of about one inch. On the other hand, according to the analysis of Rosen (1965), the ineffective length, δ , which specifies the layer thickness in Equation (1), is usually between 10 and 40 microns. This brings into question the validity of the value of β , as obtained from fiber tensile tests, in predicting the strength of composites.

The second argument deals with the absence of load concentration effects in Equation (1). Zweben (1968) and Zweben and Rosen (1970), attempted to modify the theory in order to account for these effects. While the overload suffered by the fibers adjacent to a broken filament does indeed play an essential role in the failure mechanism, the above works still do not provide a satisfactory agreement with experiments (Prewo, 1986).

The above observations show that there may be factors which are overlooked by the previous analyses. Among these we would particularly note the randomness of the fiber location in the transverse plane. Typical micrographs, for graphite/BMI and graphite/epoxy composites are shown in Figures (1a) and (1b), while results of Monte-Carlo simulations are exhibited in Figures (2a) and (2b). It is obvious that since fibers are not uniformly spaced within the cross sections, the concentric shear-lag model does not account for this commonplace phenomenon within composites.

The eccentric model, introduced herein, reveals essential effects induced by the above mentioned randomness. The present investigation indicates that in contrast with the premises of bundle theory, the failure of a filament in a composite causes a complicated stress field in the vicinity of break. Specifically, the neighboring fibers suffer extensive bending, in addition to tension, and may therefore be subjected to failure mechanisms other than those associated with pure tension. Though bending in neighboring fibers occurs even in concentric configurations around a broken filament, eccentricity serves to accentuate bending effects. It is shown in the present paper that, with rather commonplace eccentricities, the overload due to bending may be quite substantial, with values of about twice those of the intact case.

Consequently, the present micromechanical analysis casts further doubt on the applicability of the commonly used statistical data obtained for free fibers in pure tension to the prediction of strength of fibrous composites.

2. ANALYSIS

Shear-lag models, which abound in the mechanics literature provide useful approximations for the mechanism of force transfer between "soft" and "hard" material components such as layered structures or fiber reinforced composite materials. The formulation of all these models derives from the common assumption that the "soft" material responds only in shear, while the "hard" matter carries normal loads alone.

When applied to load transfer mechanisms in uniaxially reinforced polymeric composites this assumption appears to provide an excellent approximation in many important circumstances. For instance, under tension parallel to the fiber direction, the fibers carry between 95 and 99 percent of the applied load. It can also be shown that their shear distortion amounts to no more than 5 percent of their normal strain.

Since our analysis of the eccentric case is constructed as a perturbation from the concentric configuration, it is helpful to formulate the concentric case in a form which is readily amenable to the perturbation scheme.

2.1 A Shear-Lag Model for the Concentric Case

Consider the central fiber "f" of radius a positioned within a perfect hexagonal array of neighboring fibers. Also, let h denote the distance between the centers of adjacent fibers and b the outer radius of the "shear zone" as shown in Figures 3a and 3b.*

^{*} Note that since $(a/b)^2 \neq v_f$ the "shear layer" a < r < b extends <u>beyond</u> the representative volume element which is used in analyses of effective properties. Therefore the two cylinders with radii a and b should not be confused with the concentric cylinders employed in "the three phase" model (Chritensen, 1979).

The fiber volume fraction is given by $v_f = 2\pi a^2/\sqrt{3} h^2$ whereby

$$h = \sqrt{2\pi \hbar (\sqrt{3} \mathbf{v}_f)} a$$
 and $b = h - a = (\sqrt{2\pi \hbar (\sqrt{3} \mathbf{v}_f)} - 1) a$

Let r, θ , z denote cylindrical coordinates and consider a perfectly hexagonal, uniaxially reinforced fibrous array of infinite extent under uniaxial stress $\sigma_z = \sigma_o$. Consider the case of a single broken fiber at z = o. The effect of this break can be analyzed by superposition of the "undisturbed" solution $(\sigma_z = \sigma_o \text{ everywhere})$ and the solution to the disturbance caused by $(\sigma_z(r,\theta,o) = -\sigma_o(o \le r \le a, o \le \theta < 2\pi)$.

The solution to the latter problem will be based upon the following assumptions:

- (a) the only non-vanishing displacement is $u_z = u_z(r, z)$.
- (b) discard the shear deformation in the broken fiber, whereby

$$u_z^f = f(z) \qquad o \le r < a \quad , \qquad o \le z < \infty \tag{2}$$

and

$$\sigma_{z}^{f} = E_{f}f'(z) \tag{3}$$

As in the Bernoulli-Euler beam theory, the shear stresses that act upon the broken fiber can be determined as a reaction, rather than from constitutive relations.

(c) discard the contribution of normal stresses to the response of the matrix region a < r < b. Consequently consider only the shear strain

$$\gamma_{rz}^m = \frac{\partial u_z^m}{\partial r}$$
, shear stress $\tau_{rz}^m = G_m \gamma_{rz}^m$ and equilibrium governed

b y

$$\frac{\partial \tau_{rz}^m}{\partial r} + \frac{\tau_{rz}^m}{r} = 0. \tag{4}$$

(d) The displacements u_z^m vanishes at r = b.

Obviously, it is necessary to satisfy the displacement continuity condition at r = a and "global" equilibrium for the broken fiber.

In view of the foregoing assumptions we construct the solution to the present problem as follows:

By hypothesis $u_z^f = f(z)$, consequently consider $u_z^m = f(z) g(r)$ $(a \le r \le h, 0 \le z < \infty)$.

From the equilibrium condition (4) we get g'' + g'/r = 0, hence $g(r) = A + B \ln r$. The conditions $u_z^m(z, a) = u_z^f(z, a)$ and $u_z^m(z, b) = 0$ yield

$$u_z^m = \frac{\ln(b/r)}{\ln(b/a)} f(z) \tag{5}$$

Finally, force equilibrium in the z direction for the fiber gives

$$\pi a^2 \frac{d\sigma_z^f}{dz} + 2\pi a \tau_{rz}^m (a, z) = 0$$
 (6)

which, upon employment of equations (3) and (5), gives

$$f^{''}(z) - \frac{k^2}{a^2} f(z) = 0 \tag{7}$$

where

$$k^2 = \frac{2G_m}{E_f \ln (b/a)}$$

Finally, the boundary conditions $\sigma_z^f = -\sigma_0$ at z = 0 and $\sigma_z^f = 0$ as $z \to \infty$ yield

$$f(z) = \frac{\sigma_0}{E_f} \frac{a}{k} e^{-k (z/a)}$$
and $\sigma_z^f = -\sigma_0 e^{-k (z/a)}$ (8)

By superposition, the total stress on the broken fiber is

$$\sigma_{z}^{f(Total)} = \sigma_{o} \left[1 - e^{-k (z/a)} \right] \tag{9}$$

2.2 Eccentric Shear Lag

It is conjectured that a reasonable estimate of the effects of random fiber spacings, exhibited in Figures 1 and 2, can be obtained by analyzing the idealized circumstance of a perfect hexagonal array consisting an eccentric central fiber as shown in Figure 4. (The circle drawn in dashed lines shows the concentric position of that fiber.) In the sequel we let $\eta = e/b$ and construct a shear-lag model which employs η as a perturbation parameter. We shall assume that the circumstance of maximum eccentricity within the idealized configuration shown in Figure 4 (when e = b - a, $\eta = (b - a)/b$) accounts for the effects of the commonplace randomness of the arrays shown in Figures 1 and 2.

Obviously, when the inner fiber breaks at z=0 the eccentricity will give rise to non-uniform shear stresses τ_{rz}^m around the fiber/matrix interface. These stresses may vary not only along the z direction, but also with the angle θ , and they attain their highest values at the place of nearest approach. Consequently, that fiber will be subject to bending moments and undergo rotations in addition to normal deformation.

In line with assumptions (a) through (d) of the previous section we consider now

$$u_{z}^{f}(r, \theta, z) = f(z) + \eta \beta(z) r \cos\theta (o \le r \le a, 0 \le \theta < 2\pi, 0 \le z < \infty)$$
 (10)

Equation (10) implies that fiber deformation satisfies the hypothesis that "planes remain planes."

Within the matrix region $a \le r \le b$ the displacement u_2^m and the shear stress τ_2^m depend on θ and equation (4) must be replaced by

$$\frac{\partial \tau_{rz}^{m}}{\partial r} + \frac{\tau_{rz}^{m}}{r} + \frac{1}{r} \frac{\partial \tau_{\theta z}^{m}}{\partial \theta} = 0 \tag{11}$$

with
$$\tau_{rz}^{m} = G_{m} \frac{\partial u_{z}^{m}}{\partial r}$$
 and $\tau_{\theta z}^{m} = G_{m} \frac{1}{r} \frac{\partial u_{z}^{m}}{\partial \theta}$ (12)

Let $u_z^m(r, \theta, z) = q(z)p(r, \theta)$ then employment of (11) and (12) yields

$$\left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2}\right) u_z^m = 0$$

whereby

$$u_z^m = p(z) \left\{ A + B \ln r + \sum_{m=1}^{\infty} \left(A_m r^m + B_m r^{-m} \right) \cos m\theta \right\}$$
 (13)

where even symmetry in θ was considered without loss of generality.

Expressions (10) and (13) are readily amenable to a solution by the perturbation method of Parnes and Beltzer (1986), employing the eccentricity η as the perturbation parameter. Although this method can be carried to any desired degree of accuracy by expanding to ever higher powers of η , we deliberately refrain from going beyond the first power in η in deriving our estimate for the effects of fiber eccentricity. We eschew the employment of higher order expansions because the idealization involved in selecting the configuration shown in Figure (4) to represent the behavior of random arrays, such as shown in Figures 1 and 2, leads us to believe that higher order mathematical accuracy may, in fact, be devoid of physical content. Nevertheless, an expansion to $O(\eta^3)$ is given in Appendix A to demonstrate the applicability of the perturbation technique.

Employment of the expression (10) and the form given in equation (13), together with the requirement that $u_z^f(a, \theta, z) = u_z^m(a, \theta, z)$ and the assumption $u_z^m(b, \theta, z) = 0$ yield

$$u_{z}^{m}(r, \theta, z) = \frac{f(z)}{\ln(b/a)} \left[\ln(b/r) + \eta \frac{a^{2} b/r - br}{b^{2} - a^{2}} \cos \theta \right]$$

$$+ \eta \beta(z) \frac{a^{2}}{b^{2} - a^{2}} \left(\frac{b^{2}}{r} - r \right) \cos \theta \qquad a \le r \le b, 0 \le \theta < 2\pi$$
(14)

The normal stress in the fiber and the shear stress in the matrix are given by

$$\sigma_{z}^{f} = E_{f} \left[f'(z) + \eta b'(z) r \cos \theta \right] \qquad 0 \le r \le a$$
 (15)

and

$$\tau_{rz}^{m} = -G_{m} \left\{ \frac{f(z)}{\ln(b/a)} \left[\frac{1}{r} + \eta b \frac{1 + a^{2}/r^{2}}{b^{2} - a^{2}} \cos \theta \right] + \eta b(z) \frac{a^{2}}{b^{2} - a^{2}} \left(1 + \frac{b^{2}}{r^{2}} \right) \cos \theta \right\} \qquad a \le r \le b$$
(16)

Force equilibrium for the fiber in the z direction reads

$$\int_0^a \int_0^{2\pi} \frac{\partial \sigma_z^f}{\partial z} \operatorname{rd} r \, d\theta + \int_0^{2\pi} \tau_{rz}^m (a, \theta, z) \, a \, d\theta = 0$$
(17)

while the moment equilibrium of the fiber about the y-axis $\left(\theta = \pm \frac{\pi}{2}\right)$ gives

$$\int_0^a \int_0^{2\pi} \frac{\partial \sigma_z^f}{\partial z} r^2 \cos \theta \, dr d\theta + \int_0^{2\pi} \tau_{rz}^m (a, \theta, z) \, a^2 \cos \theta \, d\theta = 0$$
 (18)

upon substitution of equations (15) and (16) in expressions (16) and (18) we obtain the following field equations for f(z) and $\beta(z)$:

$$f''(z) - \frac{k^2}{a^2} f(z) = 0$$
 , $k^2 = \frac{2G_m}{E_f \ln(b/a)}$ (19)

and

$$\beta''(z) - \frac{l^2}{a^2}\beta(z) - \frac{n^2}{a^2}f(z) = 0$$
 (20)

where
$$l^2 = \frac{4Gm}{E_f} \frac{a^2 + b^2}{b^2 - a^2}$$
, $n^2 = \frac{8Gm}{E_f} \frac{b}{(b^2 - a^2) \ln(b/a)}$

Note that equation (19) is identical with the concentric result given in equation (6). When higher order expansions in η are employed this is no longer the case and the field equations for f(z) and $\beta(z)$ are fully coupled. The uncoupling in equation (19) occurs because the lowest order correction to u^f_z is $0 (\eta^2)$.

For an extended medium and a semi-infinitely long broken fiber, $0 \le z < \infty$, we have $f(z) = Ae^{-k(z/a)}$ and the boundary condition at z = 0

$$\int_0^a \int_0^{2\pi} \sigma f_2(r, \theta, 0) r dr d\theta = -\pi a^2 \sigma_0$$

which, together with expression (14) gives $A = \frac{\sigma_0}{E_f} \frac{d}{k}$ whereby

$$f(z) = \frac{\sigma_0}{E_f} \frac{a}{k} e^{-k(z/a)}$$
 (21)

as in equation (8).

Since the disturbance introduced by fiber breakage involves no applied moment at z = 0, we have

$$\int_0^a \int_0^{2\pi} \sigma^f_z(r, \theta, 0) r^2 \cos \theta dr d\theta = 0$$

whereby, in view of equation (15), we obtain the boundary condition

$$\beta'(0) = 0 \tag{22}$$

Substituting (21) into (20), together with the condition (22) and the requirement that $\lim_{z \to \infty} \beta(z) = 0$ we obtain after several manipulations:

$$\beta(z) = \frac{n^2}{k^2 - l^2} \frac{\sigma_0}{E_f} \left[\frac{a}{k} e^{-k(z/a)} - \frac{a}{l} e^{-l(z/a)} \right]$$
 (23)

For realistic values of v_f (0.4 < v_f < 0.7) k and l are of similar magnitude.

With f(z) and $\beta(z)$ thus determined, equations (10), (14) - (16), provide the "complete" solution to the perturbed field caused by the break of the inner fiber. The total field is given by adding $\sigma_z^f = \sigma_0$ to expression (15).

We are now in a position to assess the overload caused in the nearest neighboring fiber, centered at r = h, $\theta = 0$. Assume that the fiber is overburdened by the shear stresses which are shed upon it over an arc of length $2\pi b/6$. As shown in Figure 5, these shear stresses correspond to

$$\tau_{rz}^{m}(b, z, \theta)$$
 spanning the range $-\alpha \le \theta \le \alpha$, where $\alpha = \frac{\pi}{12} + \alpha'$ and

$$\tan \alpha' = \frac{d}{\sqrt{3}a} = \frac{h/2 - a}{\sqrt{3}a}.$$

The overload (force) is given by

$$N(z) = \int_{-\alpha}^{z} \int_{-\alpha}^{\alpha} \tau \, r_{z}^{m}(b, \, \theta, \, z) \, bd\theta dz \tag{24}$$

Substitution of equations (16), (21) and (23) into expression (24) yields, after several manipulations

$$N(z) = \sigma_0 a^2 \left\{ \alpha e^{-k(z/a)} - \eta \sin \alpha \left[\left(\frac{b^2 + a^2}{b^2 - a^2} - \frac{8a^2b^2}{\left(b^2 - a^2\right)c^2} \ln \left(\frac{b}{a} \right) \right] e^{-k(z/a)} + \frac{4a^2b^2}{\left(a^2 + b^2\right)c^2} e^{-l(z/a)} \right] \right\}$$
(25)

In (25)
$$c^2 = 2(a^2 + b^2) \ln(b/a) - (b^2 - a^2)$$

In addition to the normal overload, the shear stresses which act at the interface between the matrix and the nearest neighboring fiber introduce bending into that fiber. To assess the bending effect assume that these shear stresses are distributed uniformly over the arc PP' shown in Figure 5. This would place the line of action of N(z) at the center of gravity of the arc PP', hence with a lever arm $\rho = 3\sqrt{3}a/2\pi$ about the center of the nearest neighboring fiber.

Combining the normal and bending effects we have an overstress on the nearest neighbor

$$\sigma_{\max}^{(z)} = \frac{N(z)}{\pi a^2} \left(1 \pm 4 \frac{\rho}{a} \right) = \frac{N(z)}{\pi a^2} \left(1 \pm \frac{6\sqrt{3}}{\pi} \right) \tag{26}$$

This expression indicates that the overload would substantially enhance the tensile stresses at the point P_c .

3. RESULTS AND CONCLUDING REMARKS

The overloads borne by the fiber which is nearest to the broken filament are shown in Figures 6 and 7 for E-glass/epoxy and graphite/epoxy, respectively. For E-glass/epoxy we took $v_f = 0.65$, $E_f = 45 \times 10^6$ psi and $G_m = 0.2 \times 10^6$ psi , while for graphite/epoxy we employed $v_f = 0.65$, $E_f = 45 \times 10^6$ psi and $G_m = 0.2 \times 10^6$ psi.

The results in Figures 6 and 7 exhibit the overstresses $S = \sigma_z/\sigma_0$ at the center of the nearest neighboring fiber, P_o , at its point of contact with the broken filament, P_c , as well as at the point which is diametrically opposite the point of contact, P_A . The total stress enhancements, as given by the factor (S + I), are shown by the curves $\sigma_C(z)/\sigma_o$ and $\sigma_A(z)/\sigma_o$ in figures 8 and 9.

Note that a maximal stress increase of about 100% occurs in both glass/epoxy and graphite/epoxy. This contrasts with rises of about 10% - 15% evaluated by Hedgepeth (1961). Furthermore, the effect of a fiber break is confined to a smaller distance in glass/epoxy than in graphite/epoxy since the higher modulus of the graphite fibers introduces a stronger stress channelling effect due to the magnified anisotropy of the composite.

An accounting for effects of overload on fibers near the broken filament was incorporated by Zweben and Rosen (1970), where all overloads were considered to be purely tensile and all fiber arrays were assumed periodic. They noted that fibers adjacent to the broken one would fail at the stress σ_f/K , where σ_f is the nominal failure stress and K denotes the overload factor. Since fibers within composites are known to break even under low load levels the consideration of overload effects appears to be realistic. This argument applies in the present work as well, with the additional proposition that stresses due to fiber bending should be incorporated in the statistical analysis. Furthermore, it should be noted that due to the randomness of fiber spacing within the transverse cross section the factor K should be viewed as a random variable and the statistical analysis should be reformulated to account for this fact. Finally, note that normal stresses exist in the matrix (and fibers) in the transverse direction in the vicinity of a fiber break. A method to determine these stresses was developed, within the context of shear lag models, by Goree and co-workers

(see, e.g., Dharani, L.R., Jones, W.F. and Goree, J.G., 1983). Obviously, such stresses would cause bending in neighboring fibers even in perfect arrays.

In view of the above considerations, it is clear that failure mechanisms quite distinct from tensile fracture can occur in fibers adjacent to a broken filament. Since it is reasonable to assume that imperfections of several kinds (such as weak, kinked, misaligned and broken fibers, debonds along fiber/matrix interfaces, voids and cracks within the matrix, etc.) are commonplace within fibrous composites, it is to be expected that the complex state of stress presented in this work should be commonly encountered in the vicinities of those imperfections. Consequently, the failure of filamentary composites may well be attributed to complex, mixed-mode mechanisms which are inherently different form those represented by the strength statistics of "dry" fiber bundles, which is associated with purely tensile response.

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APPENDIX A: The Perturbation Expansion

Consider two eccentric circles of radii a and b, respectively and with eccentricity e as shown in Figure A-1.

As indicated in Equations (2) and (5), the solution to the concentric shearlag problem is given by

$$u_z^f = u_z^f(z) = f(z) \tag{A-1}$$

$$u_z^m = u_z^m(r, z) = \frac{\ln(b/r)}{\ln(b/a)} f(z)$$
 (A-2)

where according to Equation 8

$$f(z) = \frac{\sigma_0}{E_f} \frac{a}{k} e^{-k(z/a)}$$
 with $k^2 = \frac{2G_m}{E_f \ln(b/a)}$ (A-3)

In the eccentric case, considerations of static equilibrium for the fiber lead to the incorporation of a bending component in its deformation. Upon assuming that undeformed cross-sectional planes of the fiber remain plane after deformation, we choose in accordance with Equation (10):

$$u_z^f = u_z^f(r, \theta, z) = f(z) + \eta \beta(z) r \cos \theta$$
 (A-4)

where $\eta = e/b$. In the sequel η serves as our perturbation parameter.*

In addition, by equation (10) - (12), equilibrium of the matrix region yields

$$u_z^m = \frac{\ln(b/r)}{\ln(b/a)} f(z) + \left[\sum_{m=1}^{\infty} \left(A_m r^m + \frac{B_m}{r^m} \right) \cos m\theta \right] p(z)$$
 (A-5)

It is now necessary to satisfy the conditions that $u_z^m = u_z^f$ at r = a and that

^{*} At first glance it may appear that the representation (A-4) is somewhat arbitrary. However, it can be shown that if one starts with $u_1^{\ell}(z) = f(z) + \hat{\beta}(z) r \cos \theta$ than a systematic expansion in η indeed yields $\hat{\beta}(z) = \eta \beta(z)$. We chose (A-4) as our starting expression to circumvent non-essential details.

 $u_r^m = 0$ on the boundary of the <u>eccentric</u> circle of radius r = b.

According to the perturbation scheme of Beltzer and Parnes (1986) the value of a function $F(r, \theta)$ on the boundary C_0 of an eccentric circle of radius b with eccentricity $\eta = e/b$ can be expressed by a perturbation expansion in η as follows

$$F/_{C_o} = F^{(o)} + \left[F^{(1)} + {}_{o}\Phi_{1}^{(o)}\right] \eta + \left[F^{(2)} + {}_{o}\Phi_{1}^{(1)} + {}_{o}\Phi_{2}^{(o)}\right] \eta^{2}$$

$$+ \left[F^{(3)} + {}_{o}\Phi_{1}^{(2)} + {}_{o}\Phi_{2}^{(1)} + {}_{o}\Phi_{3}^{(o)}\right] \eta^{3} + \dots$$
(A.6)

where, in the present case

$${}_{O}\Phi_{1}^{(j)} = -b \cos \theta \, F_{r}^{(j)} \quad , \quad {}_{O}\Phi_{2}^{(j)} = \frac{b}{2} \left[b \cos^{2} \theta \, F_{rr}^{(j)} - \sin^{2} \theta \, F_{r}^{(j)} \right]$$
and
$${}_{O}\Phi_{3}^{(j)} = \frac{b^{2}}{2} \cos \theta \left[\sin^{2} \theta \, F_{rr}^{(j)} - \frac{b}{3} \cos^{2} \theta \, F_{rrr}^{(j)} \right] \tag{A-7}$$

In the present problem the function $F^{(o)}$ is given in equation (A-4), and the boundary condition at $u_z^m/c_o = o$ is satisfied by the employment of expressions (A-6) and (A-7). On the other hand the continuity condition $u_z^m = u_z^f$ at r = a does <u>not</u> involve the perturbation scheme since, by hypothesis, r = a is a "concentric boundary." Obviously, the presence of two functions of z, f(z) and $\beta(z)$, in equation (A-4) will necessitate two series expansions in (A-5) (to assure $u_z^m = u_z^f$ at r = a). Denote the two series expansions by

$$\left[\sum_{m=1}^{\infty} \left(A_m r^m + \frac{B_m}{r^m}\right) \cos m\theta\right] f(z)$$
and
$$\left[\sum_{m=1}^{\infty} \left(\overline{A_m} r^m + \frac{\overline{B_m}}{r^m}\right) \cos m\theta\right] \beta(z), \text{ respectively.}^*$$
(A-8)

Then, a systematic application of the conditions $u_z^m/C_o = 0$ and $u_z^m(a, \theta, z) = u_z^f(a, \theta, z)$ yields

^{*} It is of course always permissible to include the "concentric" solution $A + E \ln r$ within the perturbation expansion whenever necessary.

$$u_{2}^{m}(r,\theta,z) = \left\{ \frac{\ln(b/r)}{\ln(b/a)} + \eta \left(A_{1}r + \frac{B_{1}}{r} \right) \cos \theta + \eta^{2} \left[C_{2}\ln(r/a) + \left(A_{2}r^{2} + \frac{B_{2}}{r^{2}} \right) \cos 2\theta \right] + \eta^{3} \left[\left(C_{3}r + \frac{D_{3}}{r} \right) \cos \theta + \left(A_{3}r^{3} + \frac{B_{3}}{r^{3}} \right) \cos 3\theta \right] \right\} f(z)$$

$$+ \left\{ \eta \frac{a^{2}}{b^{2} - a^{2}} \cdot \frac{b^{2} - r^{2}}{r} \cos \theta + \left(\overline{A_{2}}r^{2} + \frac{\overline{B_{2}}}{r^{2}} \right) \cos 2\theta \right] + \eta^{2} \left[\overline{K_{0}} \ln(r/a) + \left(\overline{A_{2}}r^{2} + \frac{\overline{B_{2}}}{r^{2}} \right) \cos 2\theta \right] + \eta^{3} \left[\left(\overline{C_{1}}r + \frac{\overline{D_{1}}}{r} \right) \cos \theta + \left(\overline{A_{3}}r^{3} + \frac{\overline{B_{3}}}{r^{3}} \right) \cos 3\theta \right] \right\} \beta(z)$$

$$+ 0 \left(n^{4} \right). \tag{A-9}$$

where, upon denoting $A_0 = \frac{1}{\ln(b/a)}$, $\overline{A} = \frac{a^2}{h^2 - a^2}$, we have

$$A_{1} = -\frac{b}{b^{2} - a^{2}} A_{o} , B_{1} = \frac{a^{2}b}{b^{2} - a^{2}} A_{o}$$

$$A_{2} = -\frac{1}{2} \frac{b^{2}}{(b^{2} - a^{2})^{2}} A_{o} , B_{2} = \frac{1}{2} \frac{a^{4}b^{2}}{(b^{2} - a^{2})^{2}} A_{o}$$

$$C_{2} = -\frac{b^{2}}{b^{2} - a^{2}} \frac{1}{\log(b/a)} A_{o}$$

$$A_{3} = -\frac{b^{3}}{3} \frac{1}{(b^{2} - a^{2})^{3}} A_{o} , B_{3} = \frac{b^{3}a^{6}}{3(b^{2} - a^{2})^{3}} A_{o}$$

$$C_{3} = -\frac{b}{b^{2} - a^{2}} \left[\frac{b^{4}}{(b^{2} - a^{2})^{2}} + \frac{b^{2}}{b^{2} - a^{2}} \frac{1}{\log(b/a)} \right] A_{o}$$

$$D_{3} = \frac{a^{2}b}{b^{2} - a^{2}} \left[\frac{b^{4}}{(b^{2} - a^{2})^{2}} + \frac{b^{2}}{b^{2} - a^{2}} \frac{1}{\log(b/a)} \right] A_{o}$$

a n d

$$\overline{K}_{o} = -\frac{b\overline{A}}{\log (b/a)} , \overline{A}_{2} = -\frac{b^{3}\overline{A}}{b^{4} - a^{4}} , \overline{B}_{2} = \frac{a^{4}b^{3}\overline{A}}{b^{4} - a^{4}}$$

$$\overline{C}_{1} = -\frac{b^{2}}{b^{2} - a^{2}} \left[1 + \frac{1}{\log (b/a)} + \frac{b^{4} + a^{4}}{b^{4} - a^{4}} \right] \overline{A}$$

$$\overline{D}_{1} = \frac{a^{2}b^{2}}{b^{2} - a^{2}} \left[1 + \frac{1}{\log (b/a)} + \frac{b^{4} + a^{4}}{b^{4} - a^{4}} \right] \overline{A}$$

$$\overline{A}_{3} = -\frac{b^{4}}{b^{6} - a^{6}} \frac{b^{4} + a^{4}}{b^{4} - a^{4}} \overline{A}$$

$$\overline{B}_{3} = \frac{a^{6}b^{4}}{b^{6} - a^{6}} \frac{b^{4} + a^{4}}{b^{4} - a^{4}} \overline{A}$$

The equilibrium of force and moment on the fiber, as given in equations (17) and (18), yield two coupled ordinary differential equations for f(z) and $\beta(z)$. It turns out that f(z) and $\beta(z)$ take now the following forms

$$f(z) = \left(\frac{\sigma_o}{E_f} \frac{a}{k} + a_2 \eta^2 + a_3 \eta^3\right) e^{-\hat{k}(z/a)} + \left(v_2 \eta^2 + v_3 \eta^3\right) e^{-\hat{l}(z/a)}$$

$$\beta(z) = \left(\beta_1 \eta + \beta_2 \eta^2 + \beta_3 \eta^3\right) e^{-\hat{k}(z/a)} + \left(\gamma_1 \eta + \gamma_2 \eta^2 + \gamma_3 \eta^3\right) e^{-\hat{l}(z/a)}$$
with $\hat{k} = k + \eta k_1 + \eta^2 k_2 + \eta^3 k_3$ $\hat{l} = l + \eta l_1 + \eta^2 l_2 + \eta^3 l_3$. (A-10)

As noted earlier, we refrain from employing the higher order results of this Appendix in our computations, because the approximations involved in our model do not warrant their use. In fact, the utilization of higher expansions may convey the fallacious impression of higher accuracy.

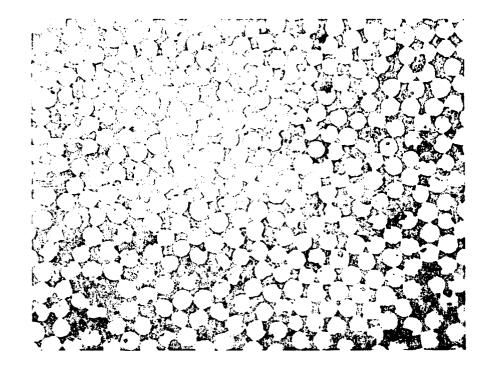
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Figure Titles:

- Fig. 1a: A typical cross-section of graphite/BMI composite, estimated volume fraction $v_f = 55\%$ (courtesy of Professor W.W. Stinchcomb) (x1000).
- Fig 1b: A typical cross-section of graphite/epoxy composite, estimated volume fraction $v_f = 65\%$ (courtesy of Professor W.W. Stinchcomb) (x1000).
- Fig. 2a: Monte-Carlo simulation of a cross-section with fiber volume fraction $v_f = 40\%$.
- Fig. 2b: Monte-Carlo simulation of a cross-section with fiber volume fraction $v_f = 65\%$.
- Fig. 3: A perfect hexagonal fibrous array, with broken central fiber f surrounded by a concentric "sleeve" m of matrix material in shear.

 (a) Cross sectional view. (b) Side view.
- Fig. 4: A hexagonal fibrous array as in figure 3, with broken eccentric fiber (f), eccentricity e, and nearest neighboring fiber (F).
- Fig. 5: Geometric considerations for evaluating the overload carried by the nearest neighboring fiber F due to the fracture of the fiber f. The load shed upon F is related to the angle α (see text).
- Fig. 6: The dimensionless overload stresses on the fiber $\widehat{F}S(P_{C,z})$, $S(P_{0,z})$ and $S(P_{A,z})$ at points P_{C} , P_{0} , and P_{A} vs. the non-dimensional distance z/a. Case of glass/epoxy, with $v_{f} = 50\%$.
- Fig. 7: Same as figure 6, but for the case of graphite/epoxy and $v_f = 65\%$.
- Fig. 8: The dimensionless stresses $\sigma_c(z)/\sigma_0$ and $\sigma_A(z)/\sigma_0$ carried by the fiber F at points P_c and P_A vs. the non-dimensional distance z/a. Case of glass/epoxy, with $v_f = 50\%$.
- Fig. 9: Same as figure 8, but for the case of graphite/epoxy and $v_f = 65\%$.



Fit.

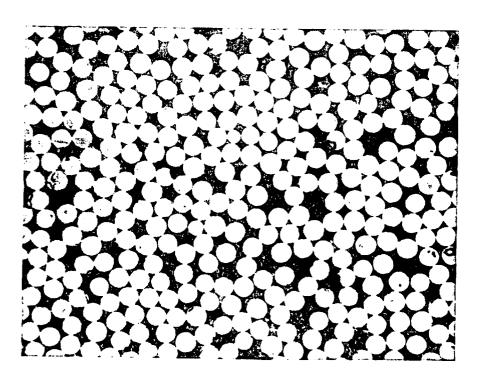


Fig. 1b

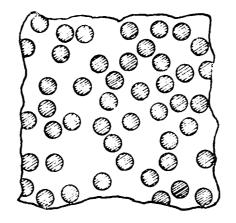


Fig. 2a

Fig. 2b

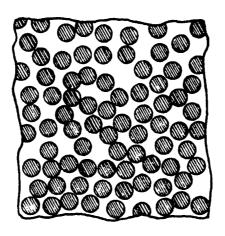


Figure 2

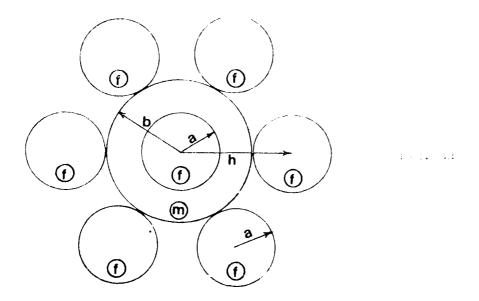


Fig. 3b

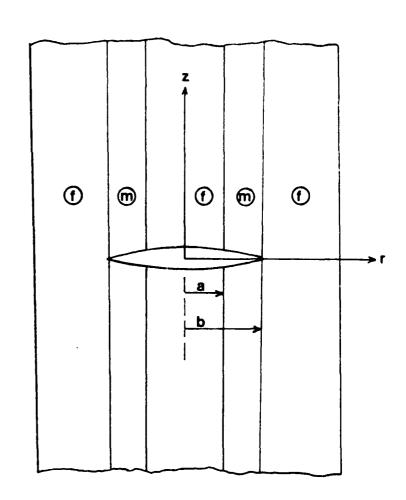
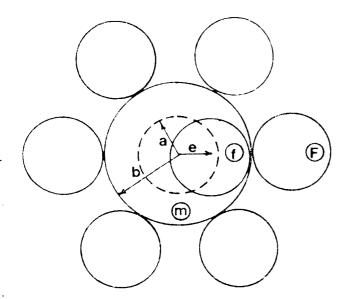


Fig. 3



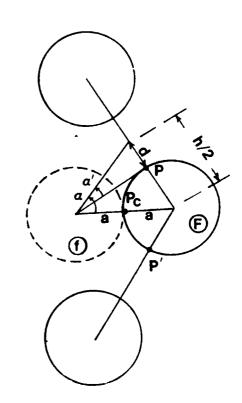


Fig. 5

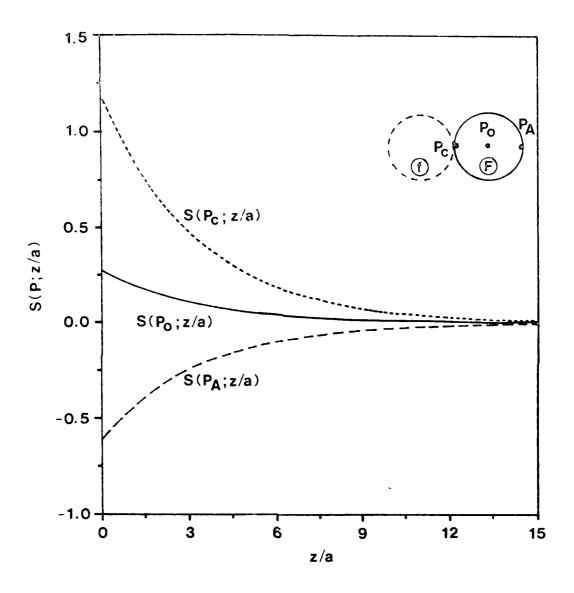


Fig. 6

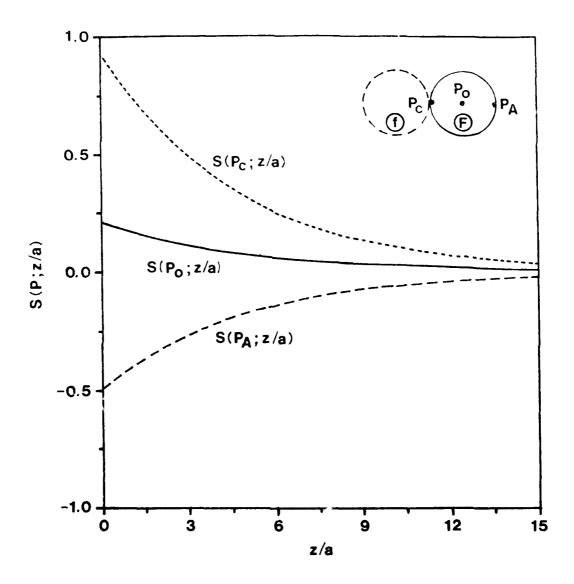


Fig. 7

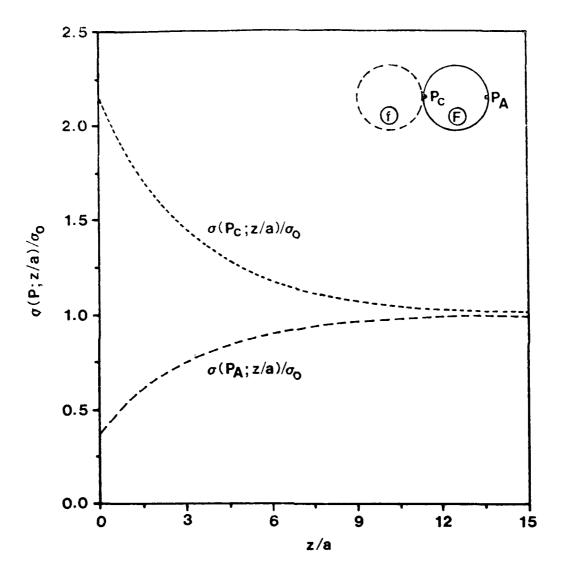


Fig. 8

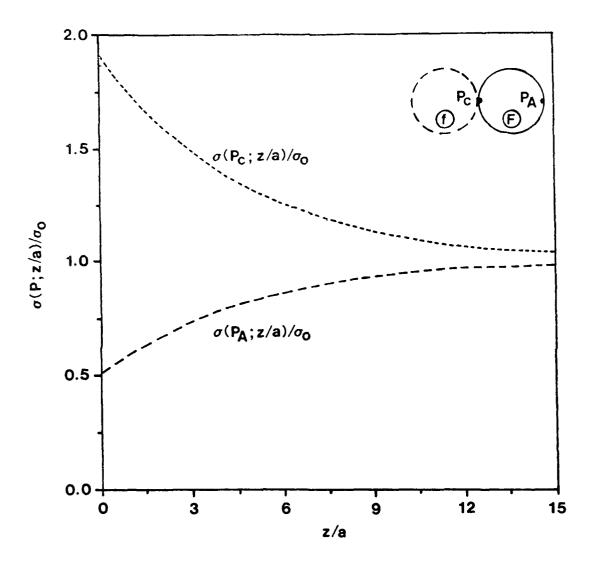


Fig. 9